

# Math 4500 HW #03 Solutions

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*This solution set is not error-free. Please email me (gl479@cornell.edu) if you spot any errors or typos!*

**Problem 1** (Exercise 2.5.4 (5 pts)). By the reflection formula, the product

$$q \mapsto u_4 \bar{u}_3 u_2 \bar{u}_1 q \bar{u}_1 u_2 \bar{u}_3 u_4$$

is a reflection in the hyperplanes orthogonal to  $u_1, u_2, u_3, u_4$  respectively. Check that  $u_4 \bar{u}_3 u_2 \bar{u}_1 = i$  and  $\bar{u}_1 u_2 \bar{u}_3 u_4 = 1$ , so the product of the four reflections is indeed  $q \mapsto iq$ .

*Solution.* Here we know that  $u_1 = i, u_2 = \frac{-1+i}{\sqrt{2}}, u_3 = k, u_4 = \frac{-j+k}{\sqrt{2}}$ , hence  $\bar{u}_1 = -i, \bar{u}_2 = \frac{-1-i}{\sqrt{2}}, \bar{u}_3 = -k, \bar{u}_4 = \frac{j-k}{\sqrt{2}}$ . Thus

$$u_4 \bar{u}_3 u_2 \bar{u}_1 = \frac{-j+k}{\sqrt{2}} (-k) \frac{-1+i}{\sqrt{2}} i = \frac{1+i}{\sqrt{2}} \frac{-1+i}{\sqrt{2}} i = i$$

and

$$\bar{u}_1 u_2 \bar{u}_3 u_4 = -i \frac{-1+i}{\sqrt{2}} (-k) \frac{-j+k}{\sqrt{2}} = \frac{j+k}{\sqrt{2}} \frac{-j+k}{\sqrt{2}} = 1.$$

□

**Problem 2** (Exercise 2.7.1 (5 pts)). Check that  $q \mapsto u^{-1}qu$  is an automorphism of  $\mathbb{H}$  for any unit quaternion  $u$ .

*Solution.* It suffices to check that  $q \mapsto u^{-1}qu$  is an isomorphism from  $\mathbb{H}$  to  $\mathbb{H}$ .

For any two quaternion  $q_1, q_2$ , we have

$$u^{-1}(q_1 q_2)u = u^{-1}(q_1(uu^{-1})q_2)u = (u^{-1}q_1u)(u^{-1}q_2u)$$

and

$$u^{-1}(q_1 + q_2)u = (u^{-1}q_1 + u^{-1}q_2)u = u^{-1}q_1u + u^{-1}q_2u$$

since the multiplication is a homomorphism. These imply that  $q \mapsto u^{-1}qu$  is a homomorphism  $\mathbb{H} \rightarrow \mathbb{H}$ .

If

$$u^{-1}q_1u = u^{-1}q_2u$$

for two quaternion  $q_1, q_2$ , then by multiplying  $u$  and  $u^{-1}$ , we know  $q_1 = q_2$  and the map is injective. For any  $q \in \mathbb{H}$ , the map sends  $uqu^{-1}$  to  $q$ . Hence it is surjective.<sup>[5]</sup> The continuity is derived from the fact that matrix multiplication is continuous. □

**Problem 3** (Exercise 3.1.2 (5 pts)). Give an example of a matrix in  $O(3)$  that is not in  $SO(3)$ , and interpret it geometrically.

*Solution.* Consider

$$A = \begin{pmatrix} 1 & & \\ & 1 & \\ & & -1 \end{pmatrix}$$

is an element in  $O(n)$ . But  $\det(A) = -1$ , which means  $A \notin SO(3)$ . Geometrically it is the reflection about the  $xOy$  plane. □

**Problem 4** (Exercise 3.2.1 (10 pts)). Bearing in mind that matrix multiplication is a continuous operation, show that if there are continuous paths in  $G$  from  $I$  to  $A \in G$  and to  $B \in G$  then there is a continuous path in  $G$  from  $A$  to  $AB$ .

*Solution.* Since  $I$  and  $B$  are path-connected, we have a path

$$\alpha : [0, 1] \rightarrow G$$

s.t.  $\alpha$  is continuous and  $\alpha(0) = I$ ,  $\alpha(1) = B$ . Since the multiplication of matrix is continuous, we have another path

$$\begin{aligned}\bar{\alpha} : [0, 1] &\rightarrow G \\ t &\mapsto A \cdot \alpha(t).\end{aligned}$$

Since  $\bar{\alpha}(0) = A$  and  $\bar{\alpha}(1) = AB$ , we know  $\bar{\alpha}$  is a path connecting  $A$  and  $AB$ . Hence  $A$  and  $AB$  are path-connected.  $\square$

**Remark.** Here it is not necessary to know the path-connectedness of  $I$  and  $B$ . However, the textbook did not give us the definition of path-connectedness, which made a lot of people confused. The formal definition is in a space  $X$ , two points  $x, y$  are said to be path-connected if there is a continuous map

$$\alpha : [0, 1] \rightarrow X$$

s.t.  $\alpha(0) = x$  and  $\alpha(1) = y$ .

**Problem 5** (Exercise 3.2.2 (5 pts)). Similarly show that if there is a continuous path in  $G$  from  $I$  to  $C$ , then there is also a continuous path from  $C^{-1}$  to  $I$ .

*Solution.* By previous exercise, put  $B = C$  and  $A = C^{-1}$ .  $\square$

**Problem 6** (Exercise 2.7.2 (0 pts)). Prove that an automorphism  $\rho$  of  $\mathbb{H}$  preserves 0 and differences.

*Solution.* Consider

$$\rho(0) = \rho(0 + 0) = \rho(0) + \rho(0),$$

thus  $\rho(0) = 0$ . For any two  $p, q \in \mathbb{H}$ , since  $\rho$  is an automorphism,  $\rho(p) = \rho(p - q + q) = \rho(p - q) + \rho(q)$ , thus it preserves the differences.  $\square$

**Problem 7** (Exercise 2.7.3 (0 pts)). Prove that an automorphism  $\rho$  of  $\mathbb{H}$  preserves 1 and quotients.

*Solution.* Similar to 2.7.2.  $\square$

**Problem 8** (Exercise 2.7.4 (0 pts)). Prove that an automorphism  $\rho$  of  $\mathbb{H}$  is a  $\mathbb{R}$  linear map.

*Solution.* First for any  $m, n \in \mathbb{Z}$  s.t.  $n \neq 0$ , we have

$$\rho(mq) = \rho(q + \cdots + q) = \rho(q) + \cdots + \rho(q) = m\rho(q)$$

and

$$n\rho\left(\frac{m}{n}q\right) = \rho\left(n\frac{m}{n}q\right) = \rho(mq) = m\rho(q),$$

therefore  $\rho\left(\frac{m}{n}q\right) = \frac{m}{n}\rho(q)$ .

For any real number  $r$ , there exists a sequence of rational numbers  $\{r_k\}_{k \in \mathbb{N}}$  s.t.  $r_k \rightarrow r$  as  $k \rightarrow \infty$ . Hence by the continuity of  $\rho$ ,

$$\rho(rq) = \rho\left(\left(\lim_{k \rightarrow +\infty} r_k\right)q\right) = \lim_{k \rightarrow +\infty} \rho(r_k q) = \lim_{k \rightarrow +\infty} r_k \rho(q) = r\rho(q).$$

$\square$